## Bridging the Global Precipitation Measurement (GPM) Level II and Level III precipitation

### using Multi-Radar/Multi-Sensor-GPM (MRMS-GPM)

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Characterization of satellite surface precipitation estimates and bridging Level-2 GPM core, constellation and combined Level-3 estimates. Needed in water cycle and extreme events studies, weather and climate prediction; over land in flood prediction and water resources.

- use the NOAA/NSSL Multi-Radar/Multi-Sensor System (MRMS) system to provide a consistent reference research framework for creating conterminous US (CONUS)-wide comparison benchmark of précipitation retrievals across GPM core and constellation satellites.
- cross-platform characterization acts as a bridge to intercalibrate active and passive microwave measurements from the GPM core satellite to the constellation satellites, and propagate to Level-3 precipitation products.

#### Space sensors

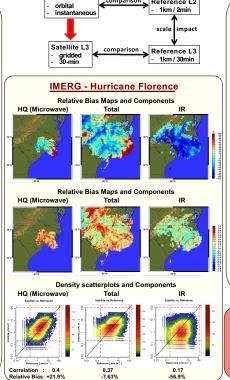
TRMM-PR/TMI, GPM-DPR/GMI, SSMIS, AMSR-2, DMSP-SSM/I, MHS, ATMS

#### Background: MRMS Comparison MRMS provides 3D reflectivity mosaics 3. Bridge across GPM sensors and the gridded Level-3 products and QPE products over CONUS at 1-km<sup>2</sup>/2analyze precipitation features sampled active sensors passive sensors min resolution by satellite sensors time platform to develop test, and assess advanced techniques in quality control, → intermittence data integration and precipitation estimation 1. consistency check 2. error analysis space vs. ground space sensors vs. reference radars http://nmg.ou.edu Reference precipitation 32 N Establish a trustworthy reference 28°N precipitation database in real-time 24 N 04/11 2011 07:25 AM → gauge adjustment 20 **Disseminating data** → quality/quantity controls → precipitation types → matching the resolution of each 80°W 130°W 120°W 110°W 100°W 90°W 70°W eo.M algorithm development & validation purposes (DPR & GMI) active & passive Level 2, Level 3 Brigding between sensors and products → used in GPROF at launch algorithm active/passive/combined level-2 and → between active and passive sensors, e.g. GPM-DPR vs. GPROF-GMI level-3 precipitation products oducts: 2A25 & 2A12 → between algorithms versions e.g. GPROF-GMI V04 vs. GPROF-GMI V05 period: March-October 2011 sample: 500 000+ Satellite L2 comparison Reference L2

# Active sensors: GPM Dual-frequency Precipitation Radar Diagnostic analysis: intermittency within the DPR footprint bright band stratiform convective Diagnostic/prognostic analysis: DPR algorithm parameter prognostic : system at 12:30 UTC on 18 April 2016 near H Evaluation over the period June 2014 – Sept. 2016 (4M\* matched DPR-MRMS estimates) brightband stratiform convective

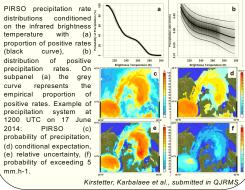
-19.5 %

-15.5 %



#### Integrated Multi-satellitE Retrievals for GPM

Satellite-based quantitative precipitation estimation (QPE) requires more than just one deterministic "best estimate" to adequately cope with the intermittent, highly skewed precipitation distribution. A new approach called Probabilistic QPE using Infrared Satellite Observations (PIRSO) is proposed to advance the use of uncertainty as an integral part of QPE. PIRSO precipitation probability maps outperform conventional deterministic QPE by mitigating biases like PERSIANN-CCS used in IMERG. PIRSO quantifies uncertainty needed for precipitation ensembles and multisensor merging, and advances the monitoring of precipitation extremes for hydrometeorological hazards



### Relevance and Broader Impact

- Evaluation & development of GPM precipitation
- propagation of uncertainties in Level 3 precipitation

Any question or comment? Please contact me at: Pierre.Kirstetter@noaa.gov